

Neven Vision Mobile Visual Search

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Why Visual Search for Mobile Phones?

Camera Phones are an Enormous Market

- More cameras are bundled with mobile phones than sold standalone or bundled with any other device
- 365 million units shipped in 2005; 903 million units forecast to ship in 2010
- 87 percent of all handsets shipped in 2010 will be camera phones
- By 2010 camera phone users will have captured a total of 228 billion images







Neven Vision Visual Search Market Activities



i-Scout[™]

From Mobile Marketing to Visual Search



Mobile Identifier[™]

In-Field Multi-Biometric Identification



Application Development

Photo Sorting, Visual Effects, etc.





i-ScoutTM Visual Mobile Search

















- Branding and direct marketing with performance feedback
 - Connect to customer at moment of interest and create lasting connection
 - Rich, multi-channel, highly interactive, repeated/reinforcing impressions
 - Customer action to initiate
 - Get tracking data, marketing feedback
- Fun, active, and highly convenient experience for consumers
- Higher click rates than in comparable SMS campaigns









Image-Based Search: Mobile Advertising

Instantaneous and Interactive







Mobile Companion: Travel Guide





Picture of a place of interest



Read history of the site Find admission prices & tour times Schedule a tour





Image-Based Search: Product Inquiry

Catering to the Mobile Lifestyle





Receive product information Customize your options Get a price quote Receive purchase rewards / feature upgrades









- **Read reviews**
 - See showtimes and purchase tickets
- Watch the trailer
- **Download ringtones**





Mobile Identifier[™] In-Field Multi-Biometric Identification





Mobile Identifier™

Security Product Fully Developed and Field Tested

"The Mobile Identifier platform is providing our officers with critical identity information at their fingertips... Every police officer needs to have one on his belt.



Commander Charlie Beck Los Angeles Police Department





Mobile IdentifierTM In-Field Identification with Multi-Biometrics



- Mobile device for in-field identification using multibiometrics
- Face and finger biometrics
- Version 2.0 integrates skin and iris recognition (SIMBA)
- Device holds up to 200,000
 records locally
- Allows for wireless WAN connectivity
- Successfully field tested with numerous organizations
- High demand for Mobile Identifier in the law enforcement, military and corporate security markets.
- Acts as force multiplier





Secret Sauce: SIMBATM Single-Image Multiple Biometric Analysis



- 2D high resolution images allow the seamless integration of Facial Feature, Skin Texture and Iris Analysis into a single recognition engine
- Required resolution in pixels between the eyes:
 - Facial feature >25*
 - Skin texture >100*
 - Iris >600*

(6 Megapixel Camera)

 Neven Vision's Facial Feature Tracking is the necessary base technology for SIMBA.

*Numbers assume a sharp image.





DoCoMo winter models 2005 are equipped with facial biometrics.







Neven Vision Technology Overview





Neven Vision Core Technology

A Broad Set of Integrated Recognition Modules



Neven Vision

Module	Technology	Applications
fD	Face Detection	photo sorting, automatic camera control: focus, zoom
ffD	Facial Feature Detection	facial gesture recognition, selection of optimal picture, redeye elimination,
ffT	Facial Feature Tracking	video special effects, character animation, video games, gaze tracking and drowsiness detection
fR	Face Recognition	physical and logical access control, surveillance systems, identity verification, photo sorting
oR	Object recognition	visual mobile search, security applications include tattoo, stolen artwork and driver license recognition
BCR	Bar Code Recognition	visual mobile search, contains licensed technology
OCR	Character Recognition	visual mobile search, contains licensed technology











Overview of Recognition Engine













Choice of Features

- Multiple feature types are employed concurrently
- A corner stone feature are Gabor Wavelets
- Motivation for the use of Gabor Wavelets
 - Good experimental results
 - Favorable signal theoretic properties
 - Optimal localization in space and frequency domain
 - Amplitude is invariant under small translations
 - Phase information for precise localization
 - Biologically plausible







Finding of Corresponding Points



1. How similar is the feature $\vec{f}(\vec{x}^c)$ extracted at \vec{x}^c to a set of sample features { $\vec{f}^G(\vec{p}_i)$ }? 2. How different is \vec{x}^G and \vec{x}^c ? 3. Which parameters \vec{p} characterize $\vec{f}(\vec{x}^c) = \vec{f}(\vec{x}^c, \vec{p})$?

Only Neven Vision employs dedicated engines to address questions 2) and 3).





Translation Engine



A neural network based translation engine proved superior over phase based translation engine but is less general.





Experimental Setup to Study Feature Manifolds



Light Stage 2.0 by Paul Debevec



3 Dof Robotic Arm by Benahm Salemi





Parameter Engine

Using parameterized feature sets is key to achieving illumination and pose invariance.







- Camera phones constitute a large and fast growing market.
- Image recognition forms the basis of new services that will become pervasive.
- Machine vision enables broad range of services: from identity management via visual search to entertainment applications

